

Lecture(s) Feb 8.

The Levi form.

Let $M \subseteq \mathbb{C}^{n+1}$ be a real (smooth) hypersurface, and $p \in M$. Let ρ be defining fun near p , i.e. M is given by $\rho=0$ and $d\rho \neq 0$ on M .

Def 1. The Levi form^{of M} w.r.t. ρ at p is the Hermitian form

$$L_p^\rho: T_p^{1,0} M \times T_p^{1,0} M \rightarrow \mathbb{C}$$

given by

$$L_p^\rho(X_p, Y_p) = \sum_{i,j=1}^n \frac{\partial^2 \rho}{\partial z_i \partial \bar{z}_j}(p) X_p^i \overline{Y_p^j},$$

where $X_p = \sum_i X_p^i \frac{\partial}{\partial z_i}$, $Y_p = \sum_j Y_p^j \frac{\partial}{\partial z_j}$.

Prop 1. Let $X_p, Y_p \in T_p^1,0M$, and let X, Y be sections (v.f.) of $T^1,0M$ extending X_p, Y_p near p . Then

$$L_p^0(X_p, Y_p) = \sqrt{-1} \partial \rho([X, \bar{Y}])|_p$$

PF. Set $\theta = \sqrt{-1} \partial \rho$. Then we note that

$$d\theta = \sqrt{-1} d\partial \rho = \sqrt{-1} \bar{\partial} \partial \rho = \sqrt{-1} \sum_{i,j} \frac{\partial^2 \rho}{\partial z_i \partial \bar{z}_j} dz_i \wedge d\bar{z}_j$$

Thus, in diff. form notation, we can write

$$L_p^0(X_p, Y_p) = -d\theta(X, \bar{Y})|_p$$

Cartan's "Magic" formula:

$$d\theta(X, \bar{Y}) = X\theta(\bar{Y}) - \bar{Y}\theta(X) - \theta([X, \bar{Y}]).$$

Now, $\theta(X) = \sum_i \frac{\partial \rho}{\partial z_i} X^i = 0$ since X is (X) a section of $T^1,0M$, and similarly $\theta(\bar{Y}) = 0$.

The conclusion follows. \square (X) see end of notes.

The way the Levi form is defined it appears to depend on the coordinates z . Let's look into this:

Let $w = H(z)$, where H is a biholom. Give $H = (H_1, \dots, H_N)$ with $N = n+1$ a hol. Invertible map near p ; $p' = H(p)$

Chain rule:

$$\frac{\partial \rho}{\partial z_i} = \sum_l \frac{\partial H^l}{\partial z_i} \frac{\partial \rho}{\partial w^l}$$

Again:

$$\frac{\partial^2 \rho}{\partial z_i \partial \bar{z}_j} = \sum_{l,k} \frac{\partial H^l}{\partial z_i} \overline{\frac{\partial H^k}{\partial z_j}} \frac{\partial^2 \rho}{\partial w^l \partial \bar{w}^k}$$

Since H is holom. $\Rightarrow \frac{\partial H^l}{\partial z_i}$ is holom.

$$\Rightarrow \frac{\partial}{\partial \bar{z}_j} \left(\frac{\partial H^l}{\partial z_i} \right) = 0$$

Thus, w/ $X_p, Y_p \in T_p^{*0} M \Rightarrow$

$$\sum_{i,j} \frac{\partial^2 \rho}{\partial z_i \partial \bar{z}_j} X_p^i \bar{Y}_p^j = \sum_{k,l} \sum_{i,j} \frac{\partial^2 \rho}{\partial w_k \partial \bar{w}_l} \frac{\partial H^k}{\partial z_i} \frac{\partial \bar{H}^l}{\partial \bar{z}_j} X_p^i \bar{Y}_p^j$$

Now

$$\sum_k \sum_l \frac{\partial H^k}{\partial z_j} X_p^i \frac{\partial}{\partial w_k} = H_k(X_p),$$

or in other words, simply X_p expressed in the coordinates w , if

$$X_p = \sum_{i=1}^n \tilde{X}_p^i \frac{\partial}{\partial w_i}, \text{ then}$$

$$\tilde{X}_p^k = \sum_i \frac{\partial H^k}{\partial z_i} X_p^i$$

With similar notation for Y , we conclude

$$\sum_{i,j} \frac{\partial^2 \rho}{\partial z_i \partial \bar{z}_j} X_p^i \bar{Y}_p^j = \sum_{k,l} \frac{\partial^2 \rho}{\partial w_k \partial \bar{w}_l} \tilde{X}_p^k \bar{\tilde{Y}}_p^l$$

We have proved

Prop 2 The Levi form ^{of M} w.r.t ρ is independent of the local coordinates chosen.

The Levi form of M does depend on ρ .

Let $\tilde{\rho}$ be another defining fun.

Then \exists smooth fun a s.t. $\tilde{\rho} = a\rho$.

We compute:

$$\frac{\partial \tilde{\rho}}{\partial z_i} = a \frac{\partial \rho}{\partial z_i} + \rho \frac{\partial a}{\partial z_i} \quad \text{and}$$

$$\begin{aligned} \frac{\partial^2 \tilde{\rho}}{\partial z_i \partial \bar{z}_j} &= a \frac{\partial^2 \rho}{\partial z_i \partial \bar{z}_j} + \frac{\partial a}{\partial \bar{z}_j} \frac{\partial \rho}{\partial z_i} + \frac{\partial a}{\partial z_i} \frac{\partial \rho}{\partial \bar{z}_j} \\ &\quad + \rho \frac{\partial^2 a}{\partial z_i \partial \bar{z}_j} \end{aligned}$$

We note that all terms in RHS vanish when we choose $p \in M$ and $X_p, Y_p \in T_p^{1,0} M$. The last term vanishes since $\rho = 0$ at p . The 2nd and 3rd terms vanish b/c $X_p, Y_p \in T_p^{1,0} M$ as in the previous proof. Thus:

Prop 3. If $\tilde{\rho} = a\rho$ is another defining function, then

$$\tilde{L}_p^{\tilde{\rho}} = a L_p^{\rho}.$$

So what is invariant on M ?

Def 2. Choose an orientation of M and let the signature $(a, b, r)_p$ be # of \wedge at p .

$+$, $-$, 0 eigenvalues of the Levi form wrt any defining fn consistent with the orientation. ∇

Prop 4. If M is ^{an} oriented real hypersurface, then the signature (a, b, r) is invariant.

Pf. Follows from Prop's 3, 4 since any two defining functions consistent w/ the orientation are related by $\beta = a\rho$ with $a > 0$. \square

Note: Here, for a hypersurface, I think of a choice of orientation as a choice of unit normal vector N (w.r.t. Euclidean metric on $\mathbb{Q}^m \cong \mathbb{R}^{2n}$), and ρ is consistent if $\nabla \rho \cdot N > 0$.

Rem. Without orientation we cannot distinguish between a, b in $(a, b, r)_p$, but r is invariant and $|a-b|$ is invariant

Def 30 A hypersurface $M \subseteq \mathbb{C}^{n+1}$ is Levi nondegenerate at $p \in M$ if $r=0$, (Levi form is nondegenerate).

② M is strictly pseudoconvex at $p \in M$ if $r=0$ and either a or b is 0 (Levi form is positive or negative definite, depending on orientation).

Rem. Since the CR dim of $M \subseteq \mathbb{C}^{n+1}$ is n , we always have $a+b+r=n$. Thus, strict convexity can be expressed invariantly wrt $(a, b, r)_p$ by $|a-b|=n$.

(*) Clarification of $\theta(\bar{Y})=0$ in pf of Prop 1. Although $d\rho \neq 0$, $d\rho(W)=0$ for all $W \in T_x M$ since $\rho=0$ on M . Hence, since $d=\partial+\bar{\partial}$, $\partial\rho(W)=-\bar{\partial}\rho(W) \Rightarrow$

$$\sqrt{-1} \partial\rho(\bar{Y}) = -\sqrt{-1} \bar{\partial}\rho(\bar{Y}) = \overline{\sqrt{-1} \partial\rho(Y)} = 0.$$